

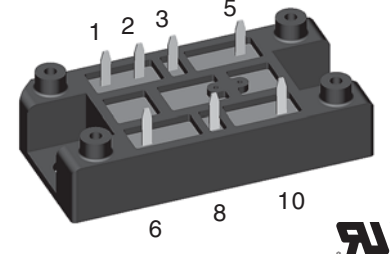
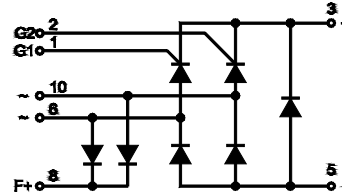
## Half Controlled Single Phase Rectifier Bridge

Including Freewheeling Diode and Field Diodes

$$V_{RRM} = 800-1600 \text{ V}$$

$$I_{dAVM} = 40 \text{ A}$$

| $V_{RSM}$<br>$V_{DSM}$<br>V | $V_{RRM}$<br>$V_{DRM}$<br>V | Type          |
|-----------------------------|-----------------------------|---------------|
| 900                         | 800                         | VHFD 37-08io1 |
| 1300                        | 1200                        | VHFD 37-12io1 |
| 1700                        | 1600                        | VHFD 37-16io1 |



### Bridge and Freewheeling Diode

| Symbol               | Conditions   | Maximum Ratings  |
|----------------------|--|--|
| $I_{dAV}$            | $T_H = 85^\circ\text{C}$ , module  | 36 A   |
| $I_{dAVM}^*$         | module   | 40 A   |
| $I_{FRMS}, I_{TRMS}$ | per leg  | 31 A   |
| $I_{FSM}, I_{TSM}$   | $T_{VJ} = 45^\circ\text{C}$ ;<br>$V_R = 0 \text{ V}$   | $t = 10 \text{ ms}$ (50 Hz), sine 320 A<br>$t = 8.3 \text{ ms}$ (60 Hz), sine 350 A  |
|                      | $T_{VJ} = T_{VJM}$<br>$V_R = 0 \text{ V}$  | $t = 10 \text{ ms}$ (50 Hz), sine 280 A<br>$t = 8.3 \text{ ms}$ (60 Hz), sine 310 A  |
| $I^2t$               | $T_{VJ} = 45^\circ\text{C}$<br>$V_R = 0 \text{ V}$   | $t = 10 \text{ ms}$ (50 Hz), sine 500 A <sup>2</sup> s<br>$t = 8.3 \text{ ms}$ (60 Hz), sine 520 A <sup>2</sup> s                    |
|                      | $T_{VJ} = T_{VJM}$<br>$V_R = 0 \text{ V}$  | $t = 10 \text{ ms}$ (50 Hz), sine 390 A <sup>2</sup> s<br>$t = 8.3 \text{ ms}$ (60 Hz), sine 400 A <sup>2</sup> s                    |
| $(di/dt)_{cr}$       | $T_{VJ} = 125^\circ\text{C}$<br>$f = 50 \text{ Hz}$ , $t_p = 200 \mu\text{s}$<br>$V_D = 2/3 V_{DRM}$<br>$I_G = 0.3 \text{ A}$ ,<br>$di_G/dt = 0.3 \text{ A}/\mu\text{s}$ | repetitive, $I_T = 50 \text{ A}$ 150 A/ $\mu\text{s}$<br>non repetitive, $I_T = 0.5 I_{dAV}$ 500 A/ $\mu\text{s}$                    |
|                      | $T_{VJ} = T_{(VJ)m}$ ; $V_{DR} = 2/3 V_{DRM}$<br>$R_{GK} = \infty$ ; method 1 (linear voltage rise)  | 1000 V/ $\mu\text{s}$  |
| $V_{RGM}$            |  | 10 V   |
| $P_{GM}$             | $T_{VJ} = T_{VJM}$<br>$I_T = 0.5 I_{dAVM}$   | $t_p = 30 \mu\text{s}$ $\leq 10 \text{ W}$<br>$t_p = 500 \mu\text{s}$ $\leq 5 \text{ W}$<br>$t_p = 10 \text{ ms}$ $\leq 1 \text{ W}$ |
|                      |  | 0.5 W  |
|                      |  | $P_{GAVM}$   |
| $T_{VJ}$             |  | -40...+125 °C  |
| $T_{VJM}$            |  | 125 °C   |
| $T_{stg}$            |  | -40...+125 °C  |
| $V_{ISOL}$           | 50/60 Hz, RMS  | $t = 1 \text{ min}$ 3000 V~<br>$t = 1 \text{ s}$ 3600 V~   |
|                      | $I_{ISOL} \leq 1 \text{ mA}$   |  |
| $d_s$                | Creep distance on surface  | 12.7 mm  |
| $d_A$                | Strike distance in air   | 9.4 mm   |
| $a$                  | Max. allowable acceleration  | 50 m/s <sup>2</sup>  |
| $M_d$                | Mounting torque (M5)<br>(10-32 UNF)  | 2-2.5 Nm   |
|                      |  | 18-22 lb.in.   |
| Weight               |  | 35 g   |

### Features

- Package with DCB ceramic base plate
- Isolation voltage 3600 V~
- Planar passivated chips
- Blocking voltage up to 1600 V
- Low forward voltage drop
- Leads suitable for PC board soldering
- UL registered E 72873

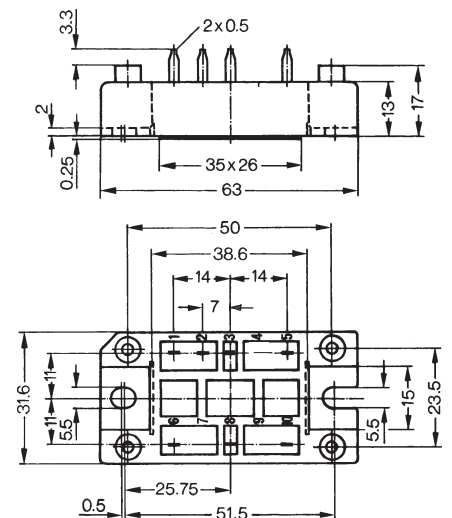
### Applications

- Supply for DC power equipment
- DC motor control

### Advantages

- Easy to mount with two screws
- Space and weight savings
- Improved temperature and power cycling

### Dimensions in mm (1 mm = 0.0394")



| Symbol     | Conditions   | Characteristic Values                           |
|------------|--|---|
| $I_R, I_D$ | $V_R = V_{RRM}; V_D = V_{DRM}$<br>$T_{VJ} = T_{VJM}$<br>$T_{VJ} = 25^\circ\text{C}$  | $\leq 5$ mA<br>$\leq 0.3$ mA                    |
| $V_T, V_F$ | $I_T, I_F = 45$ A; $T_{VJ} = 25^\circ\text{C}$   | $\leq 1.45$ V                                   |
| $V_{T0}$   | For power-loss calculations only ( $T_{VJ} = 125^\circ\text{C}$ )  | 0.85 V  |
| $r_T$      |  | 13 m $\Omega$                                   |
| $V_{GT}$   | $V_D = 6$ V;<br>$T_{VJ} = 25^\circ\text{C}$<br>$T_{VJ} = -40^\circ\text{C}$  | $\leq 1.0$ V<br>$\leq 1.2$ V                    |
| $I_{GT}$   | $V_D = 6$ V;<br>$T_{VJ} = 25^\circ\text{C}$<br>$T_{VJ} = -40^\circ\text{C}$<br>$T_{VJ} = 125^\circ\text{C}$  | $\leq 65$ mA<br>$\leq 80$ mA<br>$\leq 50$ mA    |
| $V_{GD}$   | $T_{VJ} = T_{VJM};$<br>$V_D = 2/3 V_{DRM}$   | $\leq 0.2$ V                                    |
| $I_{GD}$   | $T_{VJ} = T_{VJM};$<br>$V_D = 2/3 V_{DRM}$   | $\leq 5$ mA                                     |
| $I_L$      | $I_G = 0.3$ A; $t_G = 30$ $\mu\text{s}$ ;<br>$di_G/dt = 0.3$ A/ $\mu\text{s}$ ;<br>$T_{VJ} = 25^\circ\text{C}$<br>$T_{VJ} = -40^\circ\text{C}$<br>$T_{VJ} = 125^\circ\text{C}$ | $\leq 150$ mA<br>$\leq 200$ mA<br>$\leq 100$ mA |
| $I_H$      | $T_{VJ} = 25^\circ\text{C}; V_D = 6$ V; $R_{GK} = \infty$  | $\leq 100$ mA                                   |
| $t_{gd}$   | $T_{VJ} = 25^\circ\text{C}; V_D = 1/2 V_{DRM}$<br>$I_G = 0.3$ A; $di_G/dt = 0.3$ A/ $\mu\text{s}$  | $\leq 2$ $\mu\text{s}$                          |
| $t_q$      | $T_{VJ} = 125^\circ\text{C}; I_T = 15$ A, $t_p = 300$ $\mu\text{s}$ , $V_R = 100$ V  | typ. 150 $\mu\text{s}$                          |
| $Q_f$      | $di/dt = -10$ A/ $\mu\text{s}$ , $dv/dt = 20$ V/ $\mu\text{s}$ , $V_D = 2/3 V_{DRM}$   | 75 $\mu\text{C}$                                |
| $R_{thJC}$ | per thyristor (diode); DC current  | 1.2 K/W   |
|            | per module   | 0.3 K/W   |
| $R_{thJH}$ | per thyristor (diode); DC current  | 1.55 K/W  |
|            | per module   | 0.39 K/W  |

## Field Diodes

| Symbol     | Conditions   | Maximum Ratings     |
|------------|--|---------------------|
| $I_{FAV}$  | $T_H = 85^\circ\text{C}$ , per Diode                                 | 4 A                 |
| $I_{FAVM}$ | per diode  | 4 A                 |
| $I_{FRMS}$ | per diode  | 6 A                 |
| $I_{FSM}$  | $T_{VJ} = 45^\circ\text{C}; V_R = 0$ V;<br>$t = 10$ ms (50 Hz), sine | 100 A               |
|            | $t = 8.3$ ms (60 Hz), sine   | 110 A               |
|            | $T_{VJ} = T_{VJM}; V_R = 0$ V;<br>$t = 10$ ms (50 Hz), sine          | 85 A                |
|            | $t = 8.3$ ms (60 Hz), sine   | 94 A                |
| $I^2t$     | $T_{VJ} = 45^\circ\text{C}; V_R = 0$ V;<br>$t = 10$ ms (50 Hz), sine | 50 A <sup>2</sup> s |
|            | $t = 8.3$ ms (60 Hz), sine   | 50 A <sup>2</sup> s |
|            | $T_{VJ} = T_{VJM}; V_R = 0$ V;<br>$t = 10$ ms (50 Hz), sine          | 36 A <sup>2</sup> s |
|            | $t = 8.3$ ms (60 Hz), sine   | 37 A <sup>2</sup> s |
| $I_R$      | $V_R = V_{RRM}; T_{VJ} = T_{VJM}$                                    | 1 mA                |
|            | $T_{VJ} = 25^\circ\text{C}$  | 0.15 mA             |
| $V_F$      | $I_F = 21$ A; $T_{VJ} = 25^\circ\text{C}$                            | 1.83 V              |
| $V_{T0}$   | For power-loss calculations only ( $T_{VJ} = 125^\circ\text{C}$ )    | 0.9 V               |
| $r_T$      |  | 50 m $\Omega$       |
| $R_{thJC}$ | per diode; DC current  | 4.4 K/W             |
| $R_{thJH}$ | per diode; DC current  | 5.2 K/W             |

Data according to IEC 60747 and refer to a single thyristor/diode unless otherwise stated.  
\* for resistive load

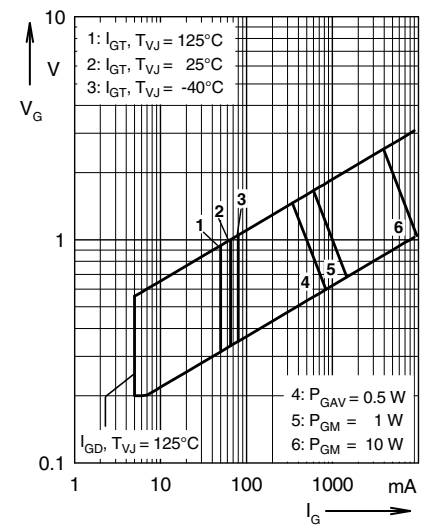


Fig. 1 Gate trigger range

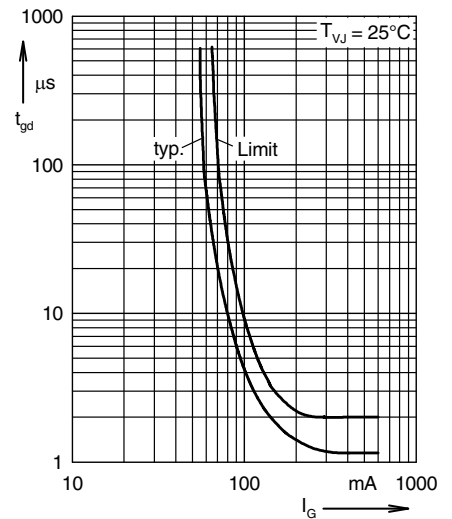


Fig. 2 Gate controlled delay time  $t_{gd}$

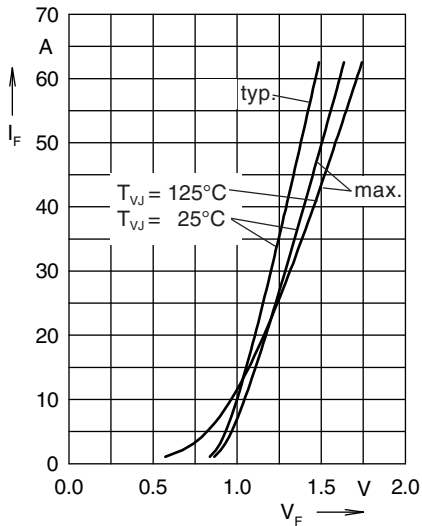


Fig. 3 Forward current vs. voltage drop per diode

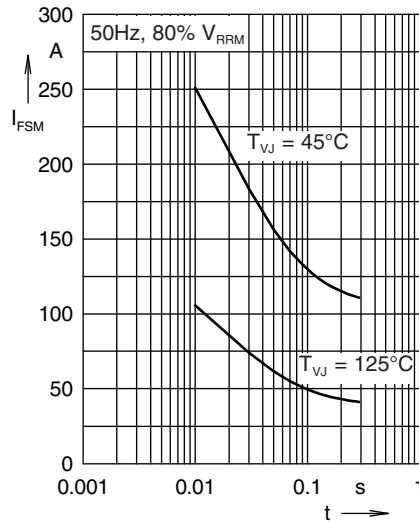


Fig. 4 Surge overload current

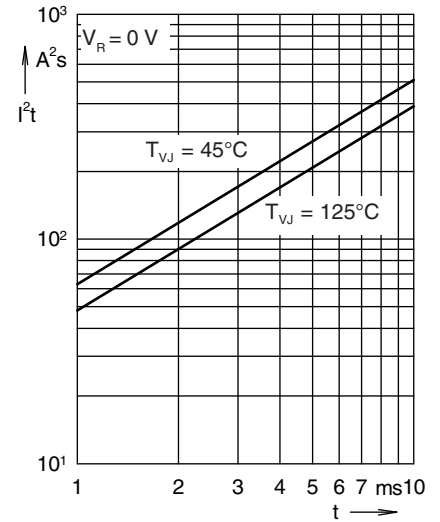


Fig. 5  $I^2t$  versus time per diode

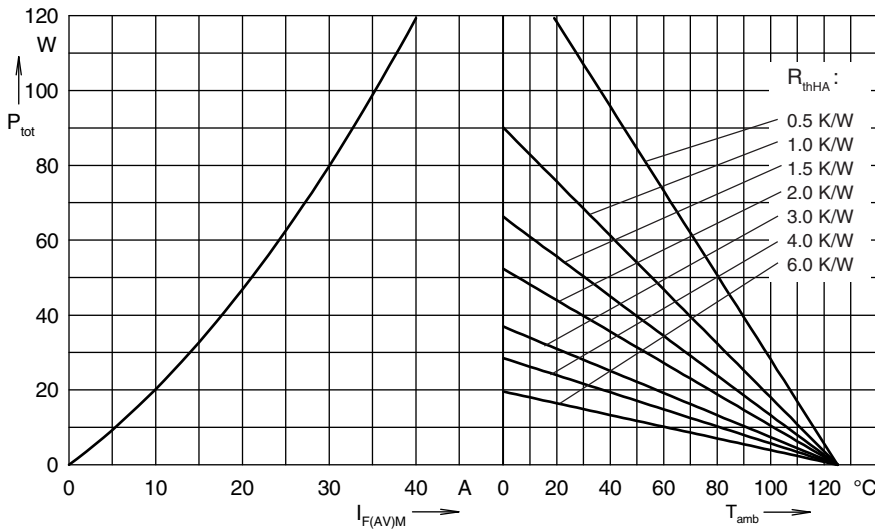


Fig. 6 Power dissipation vs. direct output current and ambient temperature

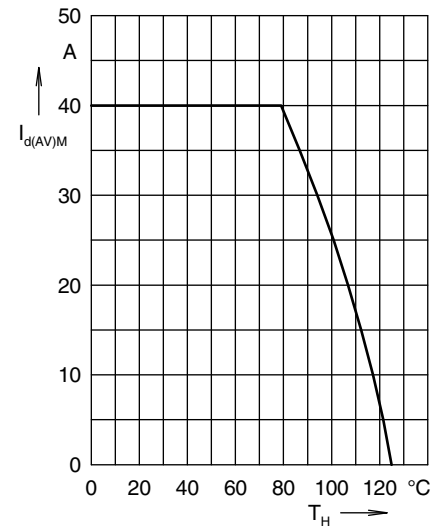


Fig. 7 Max. forward current vs. heatsink temperature

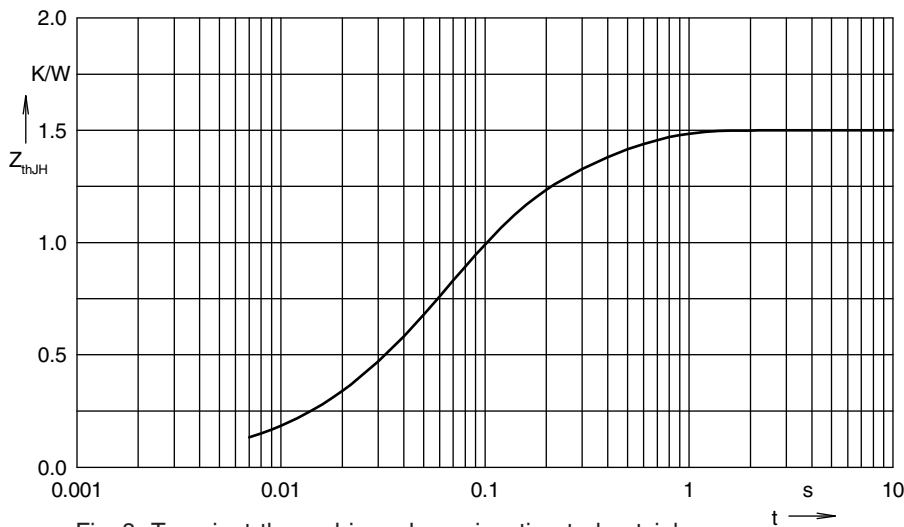


Fig. 8 Transient thermal impedance junction to heatsink

Constants for  $Z_{thJH}$  calculation:

| i | $R_{thi}$ (K/W) | $t_i$ (s) |
|---|-----------------|-----------|
| 1 | 0.005           | 0.008     |
| 2 | 0.2             | 0.05      |
| 3 | 0.875           | 0.06      |
| 4 | 0.47            | 0.25      |